

# 1 Why demand analysis/estimation?

- Estimation of demand functions is an important empirical endeavor. Why?
- Fundamental empirical question: how much market power do firms have?
  - Market power: ability to raise prices profitably. (What market power do price-taking firms have?)
  - Market power measured by markup:  $\frac{p-mc}{p}$ .
  - Problem:  $mc$  not observed!
  - Motivates empirical methodology in IO.
  - For example, you observe high prices in an industry. Is this due to market power, or due to high costs? Cannot answer this question directly, because we don't observe costs.
- *Indirect approach*: obtain estimate of firms' markups by estimating firms' demand functions.
- Intuition is most easily seen in monopoly example:
  - $\max_p pq(p) - C(q(p))$ , where  $q(p)$  is demand curve.
  - FOC:  $q(p) + pq'(p) = C'(q(p))q'(p)$
  - At optimal price  $p^*$ , **Inverse Elasticity Property** holds:

$$(p^* - MC(q(p^*))) = -\frac{q(p^*)}{q'(p^*)}$$

or

$$\frac{p^* - mc(q(p^*))}{p^*} = -\frac{1}{\epsilon(p^*)},$$

where  $\epsilon(p^*)$  is  $q'(p^*)\frac{p^*}{q(p^*)}$ , the price elasticity of demand.

- Hence, if we can estimate  $\epsilon(p^*)$ , we can infer what the markup  $\frac{p^* - mc(q(p^*))}{p^*}$  is, even when we don't observe the marginal cost  $mc(q(p^*))$ .

- Caveat: validity of exercise depends crucially on using the right supply-side model (in this case: monopoly without entry possibility).

If costs were observed: markup could be estimated directly, and we could test for validity of monopoly pricing model (ie. test whether markup =  $\frac{-1}{\epsilon}$ ).

- Start by reviewing some econometrics. (No attempt to be exhaustive.)

## 2 Primer: Least-squares estimation

- Observe data points  $\{y_i, x_i\}$  for  $i = 1, \dots, n$ . What is *linear* relationship between  $y$  and  $x$ ?
- Graph. What linear function of  $x$  – that is,  $\alpha + \beta x$  – fits  $y$  the best?
- Ordinary least squares (OLS) regression:

$$\min_{\alpha, \beta} \sum_i [y_i - \alpha - \beta x_i]^2.$$

- In multivariate case:  $X_i$  and  $\vec{\beta}$  are both  $K$  – *dimensional vectors*. Then

$$\min_{\alpha, \vec{\beta}} \sum_i [y_i - \alpha - X_i' \vec{\beta}]^2.$$

To analyze properties of OLS regression, consider a closely-related statistical problem of **Best Linear Prediction**,

Consider two random variables  $X$  and  $Y$ . What is the “best” predictor of  $Y$ , among all the possible linear functions of  $X$ ?

“Best” linear predictor minimizes the mean squared error of prediction:

$$\min_{\alpha, \beta} E(Y - \alpha - \beta X)^2. \tag{1}$$

(Recall: expectation is linear operator, so that  $E(A + B) = EA + EB$ )

The first-order conditions are:

$$\text{For } \alpha: 2\alpha - 2EY + 2\beta EX = 0$$

$$\text{For } \beta: 2\beta EX^2 - 2EXY + 2\alpha EX = 0.$$

Solving:

$$\begin{aligned}\beta^* &= \frac{Cov(X, Y)}{VX} \\ \alpha^* &= EY - \beta^* EX\end{aligned}\tag{2}$$

where

$$Cov(X, Y) = E[(X - EX)(Y - EY)] = E(XY) - EX \cdot EY$$

and

$$VX = E[(X - EX)^2] = E(X^2) - (EX)^2.$$

**Additional implications of b.l.p.:** Let  $\hat{Y} \equiv \alpha^* + \beta^* X$  denote a “fitted value” of  $Y$ , and  $U \equiv Y - \hat{Y}$  denote the “residual” or prediction error:

- $EU = 0$
- $V\hat{Y} = (\beta^*)^2 VX = (Cov(X, Y))^2 / VX = \rho_{XY}^2 VY$
- $VU = VY + (\beta^*)^2 VX - 2\beta^* Cov(X, Y) = VY - (Cov(X, Y))^2 / VX = (1 - \rho_{XY}^2) VY$

Hence, the b.l.p. accounts for a  $\rho_{XY}^2$  proportion of the variance in  $Y$ ; in this sense, the correlation measures the linear relationship between  $Y$  and  $X$ .

Also note that

$$\begin{aligned}
Cov(\hat{Y}, U) &= Cov(\hat{Y}, Y - \hat{Y}) \\
&= E[(\hat{Y} - E\hat{Y})(Y - \hat{Y} - EY + E\hat{Y})] \\
&= E[(\hat{Y} - E\hat{Y})(Y - EY) - (\hat{Y} - E\hat{Y})(\hat{Y} - E\hat{Y})] \\
&= Cov(\hat{Y}, Y) - V\hat{Y} \\
&= E[(\alpha^* + \beta^*X - \alpha^* - \beta^*EX)(Y - EY)] - V\hat{Y} \quad (3) \\
&= \beta^*E[(X - EX)(Y - EY)] - V\hat{Y} \\
&= \beta^*Cov(X, Y) - V\hat{Y} \\
&= Cov^2(X, Y)/VX - Cov^2(X, Y)/VX \\
&= 0.
\end{aligned}$$

Hence, for any random variable  $X$ , the random variable  $Y$  can be written as the sum of a part which is a linear function of  $X$ , and a part which is uncorrelated with  $X$ .

Also,

$$Cov(X, U) = 0. \quad (4)$$

Note: in practice, with a finite sample of  $Y, X$ , the minimization problem (1) is infeasible. In practice, we minimize the sample counterpart

$$\min_{\alpha, \beta} \sum_i (Y_i - \alpha - \beta X_i)^2 \quad (5)$$

which is the objective function in ordinary least squares regression. The OLS values for  $\alpha$  and  $\beta$  are the finite-sample versions of Eq. (2).

(In “sample” version, expectations are replaced by sample averages. eg. mean  $Ex$  is replaced by sample average from  $n$  observations  $\bar{X}_n \equiv \frac{1}{n} \sum_i X_i$ . Law of large numbers say this approximation should not be bad, especially for large  $n$ .)



Next we can see some intuition of least-squares regression. Assume that the “true” model describing the generation of the  $Y$  process is:

$$Y = \alpha + \beta X + \epsilon, \quad E\epsilon = 0. \quad (6)$$

What we mean by true model is that this is a causal model in the sense that a one-unit increase in  $X$  would raise  $Y$  by  $\beta$  units. (In the previous section, we just assume that  $Y, X$  move jointly together, so there is no sense in which changes in  $X$  “cause” changes in  $Y$ .)

Question: under what assumptions does doing least-squares on  $Y, X$  (as in Eqs. (1) or (5) above) recover the true model; ie.  $\alpha^* = \alpha$ , and  $\beta^* = \beta$ ?

- For  $\alpha^*$ :

$$\begin{aligned} \alpha^* &= EY - \beta^* EX \\ &= \alpha + \beta EX + E\epsilon - \beta^* EX \end{aligned}$$

which is equal to  $\alpha$  if  $\beta = \beta^*$ .

- For  $\beta^*$ :

$$\begin{aligned} \beta^* &= \frac{Cov(\alpha + \beta X + \epsilon, X)}{VarX} \\ &= \frac{1}{VarX} \cdot \{E[X(\alpha + \beta X + \epsilon)] - EX \cdot E[\alpha + \beta X + \epsilon]\} \\ &= \frac{1}{VarX} \cdot \{\alpha EX + \beta EX^2 + E[\epsilon X] - \alpha EX - \beta[EX]^2 - EXE\epsilon\} \\ &= \frac{1}{VarX} \cdot \{\beta[EX^2 - (EX)^2] + E[\epsilon X]\} \end{aligned}$$

which is equal to  $\beta$  if

$$E[\epsilon X] = 0. \quad (7)$$

This is an “exogeneity” assumption, that (roughly)  $X$  and the disturbance term  $\epsilon$  are uncorrelated. Under this assumption, the best linear predictors from the infeasible

problem (1)) coincide with the true values of  $\alpha$ ,  $\beta$ . Correspondingly, it turns out that the feasible finite-sample least-squares estimates from (5) are “good” (in some sense) estimators for  $\alpha$ ,  $\beta$ .

Note that the orthogonality condition (7) differs from the zero covariance property (4), which is a feature of the b.l.p.

When there is more than one  $X$  variable, then we use *multivariate regression*. In matrix notation, true model is:

$$Y_{n \times 1} = X_{n \times k} \beta_{k \times 1} + \epsilon_{n \times 1}.$$

The least-squares estimator for  $\beta$  is

$$\beta^{OLS} = (X'X)^{-1} X'Y.$$

Next we consider estimating demand functions, where exogeneity is usually violated.

### 3 Demand estimation

Linear demand-supply model:

$$\begin{aligned} \text{Demand: } q_t^d &= \gamma_1 p_t + \mathbf{x}'_{t1} \beta_1 + u_{t1} \\ \text{Supply: } p_t &= \gamma_2 q_t^s + \mathbf{x}'_{t2} \beta_2 + u_{t2} \\ \text{Equilibrium: } q_t^d &= q_t^s \end{aligned}$$

Demand function summarizes consumer preferences; supply function summarizes firms' cost structure

First, focus on estimating demand function:

$$\text{Demand: } q_t = \gamma_1 p_t + \mathbf{x}'_{t1} \beta_1 + u_{t1}$$

If  $u_1$  correlated with  $u_2$ , then  $p_t$  is endogenous in demand function: cannot estimate using OLS. Graph. Several estimation approaches.

## 1. Instrumental variable (IV) methods:

- Assume there are instruments  $Z$  which satisfy certain properties
  - (a) Uncorrelated with error term in demand equation:  $E(u_1 Z) = 0$ . **Exclusion** restriction. (“order condition”)
  - (b) Correlated with endogenous variable:  $Cov(Z, p) \neq 0$ . (“rank condition”)
- The  $x$ ’s are exogenous variables which can serve as instruments:
  - (a)  $x_{t2}$  are *cost shifters*; affect production costs. Correlated with  $p_t$  but not with  $u_{t1}$ : use as instruments in demand function.
  - (b)  $x_{t1}$  are *demand shifters*; affect willingness-to-pay, but not a firm’s production costs. Correlated with  $q_t$  but not with  $u_{t2}$ : use as instruments in supply function.
- Two-stage least squares:

$$\beta^{2sls} = (\hat{X}'\hat{X})^{-1}\hat{X}'Y$$

where  $\hat{X} \equiv Z'(Z'Z)^{-1}(Z'X)$  are the predicted values of  $X$  from a least-squares regression of  $X$  on  $Z$ .

## 2. Maximum likelihood (more technical):

- Likelihood function of the data is joint density of the endogenous variables  $(\mathbf{q}_t, \mathbf{p}_t)$  conditional on exogenous variables  $(\mathbf{x}_{t1}, \mathbf{x}_{t2})$ .
- First, need to express endogenous variables in terms of exogenous variables:

$$\text{Demand: } q_t = \gamma_1 p_t + \mathbf{x}'_{t1} \beta_1 + u_{t1}$$

$$\text{Supply: } p_t = \gamma_2 q_t + \mathbf{x}'_{t2} \beta_2 + u_{t2}$$

$$\Rightarrow \begin{pmatrix} 1 & -\gamma_1 \\ -\gamma_2 & 1 \end{pmatrix} \begin{pmatrix} q \\ p \end{pmatrix} = \begin{pmatrix} \beta_1 & 0 \\ 0 & \beta_2 \end{pmatrix} \begin{pmatrix} x_{t1} \\ x_{t2} \end{pmatrix} + \begin{pmatrix} u_{t1} \\ u_{t2} \end{pmatrix}$$

$$\Leftrightarrow \Gamma Y = BX + U \Leftrightarrow Y = \Gamma^{-1}BX + \Gamma^{-1}U$$

This is called the “reduced form” representation of the demand-supply system.

- Assume that the unobservables  $\{(u_{t1}, u_{t2})_{t=1}^T\}$  are distributed according to a density function  $g(\dots)$ .

Example:  $(u_{t1}, u_{t2}) \sim \text{i.i.d } N(0, \Sigma)$

Then joint density of  $\vec{u}$  is:

$$g(\vec{u}) = (2\pi)^{-1} |\Sigma|^{-1/2} \exp \left[ -\frac{1}{2} (\vec{u})' \Sigma^{-1} (\vec{u}) \right].$$

- Recall change of variables formula: if  $Y = X/a$  and  $X$  has density function  $g(X)$ , then  $Y$  has density function

$$f(Y) = g(aY) \cdot a.$$

Applying the multivariate version of this, we get

$$f(Y) = g(\Gamma Y - BX) * |\Gamma| \quad (8)$$

Assuming you have  $T$  observations of  $(Y_t, X_t)$ , then likelihood function is

$$L(Y|X) = \prod_{t=1}^T f(Y_t) = |\Gamma|^T \prod_{t=1}^T g(\Gamma Y_t - BX_t).$$

Log-likelihood function is (ignoring the constant):

$$\log L(Y | X) \sim T \log |\Gamma| - \frac{T}{2} \log |\Sigma| - \sum_t \frac{1}{2} (\Gamma Y_t - BX_t)' \Sigma^{-1} (\Gamma Y_t - BX_t)$$

- Maximize this with respect to  $\Gamma, B, \Sigma$  to obtain maximum likelihood estimator.